Reflector antenna problem

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1

Motivation



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Pb : find the reflector surface



Punctual light at origin o, μ measure on S_o^2 Prescribed far-field: ν on S_∞^2



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Snell's law

$$T_R: x \in \mathcal{S}_0^2 \mapsto y = x - 2\langle x | n \rangle n$$



Brenier formulation $T_{\sharp}\mu = \nu$

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highly non linear



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Existence

Caffarelli & Oliker 94

Regularity, uniqueness Wang 96, Guan & Wang 98



Punctual light at origin o, μ measure on \mathcal{S}_o^2



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Prescribed far-field:
$$\nu = \nu_1 \delta_{y_1}$$
 on \mathcal{S}^2_{∞}



Punctual light at origin o, μ measure on S_o^2 Prescribed far-field: $\nu = \nu_1 \delta_{y_1}$ on S_∞^2 R : paraboloid of direction y_1 and focal O



Punctual light at origin o, μ measure on S_o^2 Prescribed far-field: $\nu = \sum_i \nu_i \delta_{y_i}$ on S_∞^2



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 $P_i(\kappa_i) =$ solid paraboloid of revolution with focal o, direction y_i and focal distance κ_i

$$R(\vec{\kappa}) = \partial \left(\bigcap_{i=1}^{N} P_i(\kappa_i) \right)$$



Decomposition of S_o^2 : $\operatorname{PI}_i(\vec{\kappa}) = \pi_{S_o^2}(R(\vec{\kappa}) \cap \partial P_i(\kappa_i))$ = directions that are reflected towards y_i .



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Problem (FF): Find $\kappa_1, \ldots, \kappa_N$ such that for every i, $\mu(\operatorname{PI}_i(\vec{\kappa})) = \nu_i$.

amount of light reflected in direction y_i .

Lemma: With
$$c(x, y) = -\log(1 - \langle x | y \rangle)$$
, and $\psi_i := \log(\kappa_i)$,
 $\operatorname{PI}_i(\vec{\kappa}) = \{x \in \mathcal{S}_0^2, \ c(x, y_i) + \psi_i \leq c(x, y_j) + \psi_j \quad \forall j\}.$

Caffarelli-Oliker '94



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$$\begin{array}{c} P_{3} \\ P_{1} \end{array} \qquad \begin{array}{c} P_{1} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{3} \\ P_{2} \\ P_{3} \\ P_{1} \\ P_{1} \\ P_{1} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{1} \\ P_{1} \\ P_{2} \\ P_{1} \\ P_{1} \\ P_{1} \\ P_{1} \\ P_{1} \\ P_{1} \\ P_{2} \\ P_{1} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{2} \\ P_{1} \\ P_{2} \\$$

► An optimal transport problem Wang '04

- $$\label{eq:multiplicative} \begin{split} \mu &= \text{probability measure on } X \\ & \text{with density, } X = \text{manifold} \end{split}$$

 $\begin{array}{l} \nu = \text{prob. measure on finite } Y \\ = \sum_{y \in Y} \nu_y \delta_y \end{array}$





Transport map: $T: X \to Y$ s.t.

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0



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Monge problem: $\mathcal{T}_c(\mu,\nu) := \min\{\mathcal{C}_c(T); T_{\#}\mu = \nu\}$

Aurenhammer, Hoffman, Aronov '98 Merigot '2010



We assume **(Twist)**, i.e. $c \in C^{\infty}$ and $\forall x \in X$ the map $y \in Y \mapsto \nabla_x c(x, y)$ is injective.

Y finite set, $\psi:Y\to \mathbb{R}$

Aurenhammer, Hoffman, Aronov '98 Merigot '2010



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Aurenhammer, Hoffman, Aronov '98 Merigot '2010



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$$T_c^{\psi}(x) = \arg\min_{y \in Y} c(x, y) + \psi(y)$$
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= generalized weighted Voronoi cell

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Aurenhammer, Hoffman, Aronov '98 Merigot '2010



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Weighted Voronoi and Optimal Transport

Aurenhammer, Hoffman, Aronov '98 Merigot '2010



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. ► Converse







Optimal transport formulation

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Cafarelli-Kochengin-Oliker'99:

coordinate-wise ascent, with minimum increment

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Initialization: Fix $y_0 \in Y$, let $\delta = \varepsilon/N$ and compute ψ s.t. $\forall y \in Y \setminus \{y_0\}, \quad \mu(\operatorname{Vor}_c^{\psi}(p)) \leq \nu_y + \delta$ **While** $\exists y \neq y_0$ such that $\mu(\operatorname{Vor}_c^{\psi}(y)) \leq \nu_y - \delta$, **do:** decrease $\psi(y)$ s.t. $\mu(\operatorname{Vor}_c^{\psi}(y)) \in [\nu_y, \nu_y + \delta]$, **Result:** ψ s.t. for all y, $|\mu(\operatorname{Vor}_c^{\psi}(y)) - \nu_y| \leq \varepsilon$.

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- ▶ Generalization of Oliker–Prussner in \mathbb{R}^2 with $c(x,y) = \|x y\|^2$

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- Complexity of SP: N^2/ε steps
- ▶ Generalization of Oliker–Prussner in \mathbb{R}^2 with $c(x, y) = ||x y||^2$
- ► Generalization: MTW⁺ costs Kitagawa '12

Concave maximization

Theorem: $\vec{\kappa}$ solves **(FF)** iff $\vec{\psi} = \log(\vec{\kappa})$ maximizes $\Phi(\psi) := \sum_{i} \int_{\operatorname{Vor}_{c}^{\psi}(y_{i})} [c(x, y_{i}) + \psi_{i}] d\mu(x) - \sum_{i} \psi_{i} \nu_{i}$ with $c(x, y) = -\log(1 - \langle x | y \rangle)$.

Aurenhammer, Hoffman, Aronov '98

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► A consequence of Kantorovich duality.

Supdifferentials. Let $\Phi : \mathbb{R}^d \to \mathbb{R}$ and $\psi \in \mathbb{R}^d$.

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•
$$\Phi$$
 concave $\Leftrightarrow \forall \psi \in \mathbb{R}^d \ \partial^+ \Phi(\psi) \neq \emptyset$.

- ▶ In this case : $\partial^+ \Phi(\psi) = \{\nabla \Phi(\psi)\}$ a.e.
- ▶ ψ maximum of $\Phi \Leftrightarrow 0 \in \partial^+ \Phi(\psi)$



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For all $\varphi \in \mathbb{R}^d$ $\min_{1 \le i \le N} [c(x, y_i) + \varphi_i] \le [c(x, y_{T_{\psi}(x)}) + \varphi_{T_{\psi}(x)}]$

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 $T_{\psi}(x) = i \Leftrightarrow x \in \operatorname{Vor}_{c}^{\psi}(y_{i})$

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For all $\varphi \in \mathbb{R}^d$ $\min_{1 \le i \le N} [c(x, y_i) + \varphi_i] \le [c(x, y_{T_{\psi}(x)}) + \varphi_{T_{\psi}(x)}]$ $\le [c(x, y_{T_{\psi}(x)}) + \psi_{T_{\psi}(x)}] + \varphi_{T_{\psi}(x)} - \psi_{T_{\psi}(x)}$

$$\begin{split} \Phi(\psi) &:= \sum_{i} \int_{\operatorname{Vor}_{c}^{\psi}(y_{i})} [c(x, y_{i}) + \psi_{i}] \,\mathrm{d}\,\mu(x) - \sum_{i} \psi_{i}\nu_{i} \\ &= \int_{\mathcal{S}^{d-1}} \min_{1 \leq i \leq N} [c(x, y_{i}) + \psi_{i}] \,\mathrm{d}\,\mu(x) - \sum_{i} \psi_{i}\nu_{i} \\ &T_{\psi}(x) = i \Leftrightarrow x \in \operatorname{Vor}_{c}^{\psi}(y_{i}) \\ \Phi(\varphi) - \Phi(\psi) \leq \int_{\mathcal{S}^{d-1}} \varphi_{T_{\psi}(x)} - \psi_{T_{\psi}(x)} \,\mathrm{d}\,\mu(x) - \sum_{i} (\varphi_{i} - \psi_{i})\nu_{i} \end{split}$$

11

$$\begin{split} \Phi(\psi) &:= \sum_{i} \int_{\operatorname{Vor}_{c}^{\psi}(y_{i})} [c(x, y_{i}) + \psi_{i}] \, \mathrm{d}\,\mu(x) - \sum_{i} \psi_{i}\nu_{i} \\ &= \int_{\mathcal{S}^{d-1}} \min_{1 \leq i \leq N} [c(x, y_{i}) + \psi_{i}] \, \mathrm{d}\,\mu(x) - \sum_{i} \psi_{i}\nu_{i} \\ &T_{\psi}(x) = i \Leftrightarrow x \in \operatorname{Vor}_{c}^{\psi}(y_{i}) \\ \Phi(\varphi) - \Phi(\psi) &\leq \int_{\mathcal{S}^{d-1}} \varphi_{T_{\psi}(x)} - \psi_{T_{\psi}(x)} \, \mathrm{d}\,\mu(x) - \sum_{i} (\varphi_{i} - \psi_{i})\nu_{i} \\ &\leq \sum_{1 \leq i \leq N} \left[\int_{\operatorname{Vor}_{c}^{\psi}(y_{i})} \, \mathrm{d}\,\mu(x) - \nu_{i} \right] (\varphi_{i} - \psi_{i}) \\ &= \langle D\Phi(\psi) | \varphi - \psi \rangle \\ & \text{with } D\Phi(\psi) = \left(\mu(\operatorname{Vor}_{c}^{\psi}(y_{i})) - \nu_{i} \right) \end{split}$$

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 $\Phi(\varphi) \leq \Phi(\psi) + \langle D\Phi(\psi) | \varphi - \psi \rangle$ with $D\Phi(\psi) = \left(\mu(\operatorname{Vor}_{c}^{\psi}(y_{i})) - \nu_{i} \right)$



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►
$$D\Phi(\psi) \in \partial^+ \Phi(\psi) \Rightarrow \Phi$$
 concave.

► $D\Phi(\psi)$ depends continuously on $\psi \Rightarrow \Phi$ of class C^1 .

► ψ maximum of $\Phi \Leftrightarrow \mu(\operatorname{Vor}_{c}^{\psi}(y_{i})) = \nu_{i} \forall i$

2. Implementation

Implementation of Convex Programming $(-\Phi)$

Quasi-Newton scheme:

Computation of descent direction / time step

LBFGS: low-storage version of the BFGS quasi-Newton scheme

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Definition: Given $P = \{p_i\}_{1 \le i \le N} \subseteq \mathbb{R}^d$ and $(\omega_i)_{1 \le i \le N} \in \mathbb{R}^N$ $\operatorname{Pow}_P^{\omega}(p_i) := \{x \in \mathbb{R}^d; i = \arg\min_j \|x - p_j\|^2 + \omega_j\}$

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Lemma: With
$$\vec{\psi} = \log(\vec{\kappa})$$
, $p_i := -\frac{y_j}{2\kappa_j}$ and $\omega_i := -\|\frac{y_j}{2\kappa_j}\|^2 - \frac{1}{\kappa_j}$,
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Proof:
$$x \in \operatorname{Vor}_{c}^{\psi}(y_{i}) \subseteq S_{o}^{2}$$

 $\iff i \in \arg\min_{j} \frac{\kappa_{j}}{1 - \langle x | y_{j} \rangle}$
 $\iff i \in \arg\min_{j} \langle x | \frac{y_{j}}{\kappa_{j}} \rangle - \frac{1}{\kappa_{j}}$
 $\iff i \in \arg\min_{j} \|x + \frac{y_{j}}{2\kappa_{j}}\|^{2} - \frac{\|y_{j}\|^{2} - \frac{1}{\kappa_{j}}\|}{-p_{j}}$
 $\iff x \in \operatorname{Pow}_{P}^{\omega}(p_{i}) \cap S^{2}$



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Complexity: $O(N \log N + C)$ where C = complexity of the Power diagram.

Numerical results (1)

 $u = \sum_{i=1}^{N} \nu_i \delta_{x_i}$ obtained by discretizing a picture of G. Monge. $\mu =$ uniform measure on half-sphere S_+^2 N = 1000



drawing of $(\operatorname{Vor}_{c}^{\psi}(y_{i}))$ (on \mathcal{S}_{+}^{2}) for $\psi = 0$

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rendering of the image reflected at infinity (using LuxRender)

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solution to the far-field reflector problem: $R(\kappa_{
m sol})$

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3. Complexity of paraboloid intersection

Theorem: For N paraboloids, the complexity of the diagram $(\operatorname{PI}_i(\vec{\kappa}))_{1 \le i \le N}$ is O(N).

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Complexity: E + F + V, where



$$E = \#$$
 edges
 $V = \#$ vertices

 $F={\rm total}~\#~{\rm of}~{\rm connected}~{\rm components}$

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 \implies the projection of $R(\vec{\kappa}) \cap \partial P_i$ on $\{y_i\}^{\perp}$ is convex $\implies \operatorname{PI}_i(\vec{\kappa})$ is connected.

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Proof:



• Every vertex has 3 edges $\Rightarrow 3V \leq 2E$.

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Proof:



- Every vertex has 3 edges $\Rightarrow 3V \leq 2E$.
- Euler's formula V E + F = 2 implies $V \le 2F - 4$ and $E \le 3F - 6$.

4. Other types of reflectors



Punctual light at origin o, μ measure on S_o^2 Prescribed far-field: $\nu = \sum_i \nu_i \delta_{y_i}$ on S_∞^2



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 $P_i(\kappa_i) = \text{convex hull of paraboloid with focal } o$, direction y_i and focal distance κ_i

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Far-field reflector antenna problem:

Problem (FF'): Find $\kappa_1, \ldots, \kappa_N$ such that for every *i*, $\mu(\text{PU}_i(\vec{\kappa})) = \nu_i$.





Punctual light at origin o, μ measure on S_o^2 Prescribed near-field: $\nu = \sum_i \nu_i \delta_{y_i}$ on \mathbb{R}^3

 $E_i(e_i) = \text{convex hull of ellipsoid with focals } o$ and y_i , and eccentricity e_i



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Near-field reflector antenna problem:

Oliker '04

Problem (NF): Find e_1, \ldots, e_N such that for every i, $\mu(\text{EI}_i(\vec{e})) = \nu_i$. amount of light reflected to the point y_i .

Complexity of a single iteration

Complexity of union/intersection of solid confocal quadric of revolutions in \mathbb{R}^3 :



Paraboloid intersection Paraboloid union Ellipsoid intersection Ellipsoid union



Conclusion

A simple quasi-Newton scheme can be used to solve rather large (15k points) geometric instances of optimal transport.
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- quantitative stability results ?

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