

Numerical optimization of Dirichlet-Laplace eigenvalues on domains in surfaces

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Geometric problem

Optimization problem

Numerical processing

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Theoretical Question : Existence of a solution (λ, u) ?

Spectral theorem: Yes!

There exist a sequence of real positive eigenvalues

$$0 < \lambda_1 \leq \lambda_2 \cdots \nearrow \infty,$$

and a sequence of associated eigenfunctions $(u_k)_{k \geq 1}$ such that

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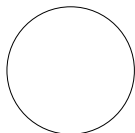
$$-\Delta u_k = \lambda_k u_k, \text{ for all } k \geq 1.$$

Moreover, the eigenfunctions (u_n) define a Hilbert basis of $H_0^1(\Omega)$.

Motivations

- ▶ The Laplace-spectrum encodes informations about the underlying domain;
- ▶ Optimization w.r.t. the domain to understand the behaviour of the spectrum.

Theoretically known examples:

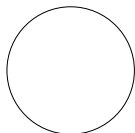


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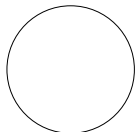
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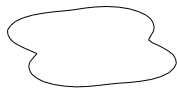


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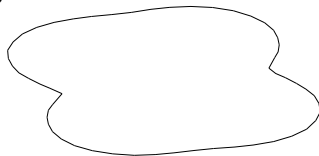


$$\lambda_{1, \text{Square}_1} \simeq 19.739$$

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$$\lambda_{1,h}(\Omega) \simeq 21.026$$



$$\lambda_{1,h}(\sqrt{2}\Omega) \simeq 10.513$$

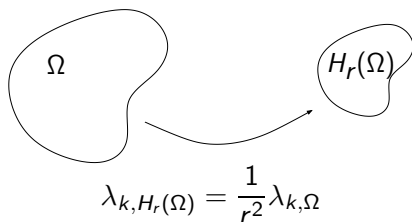
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Question : What bounded domain $\Omega \subset \mathbb{R}^2$ minimizes $\lambda_{k,\Omega}$?

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↪ That is not a good question !



(the larger Ω is, the smaller the eigenvalue $\lambda_{k,\Omega}$ is)

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Or equivalently,

$$\min_{\substack{\text{vol}(\Omega)=1, \\ \Omega \text{ bounded}}} \lambda_{k,\Omega} \Leftrightarrow \min_{\Omega \text{ bounded}} \text{vol}(\Omega) \lambda_{k,\Omega}$$

Few known results:

Theorem (Faber-Krahn, 1923)

Let B be the ball of volume 1. Then,

$$\lambda_{1,B} = \min \{ \lambda_{1,\Omega} \mid \Omega \subset \mathbb{R}^2, \text{vol}(\Omega) = 1 \} .$$



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Theorem (Krahn-Szegő, 1926)

Let B_2 be the union of two identical balls, $\text{vol}(B_2) = 1$. Then,

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- These theorems also hold in \mathbb{R}^n , $n \geq 3$;

Another result:

Theorem (Bucur 2012 & Mazzoleni, Pratelli 2013)

There exists a minimizer for $\lambda_{k,\Omega}$, $k \geq 3$, among all quasi-open sets Ω of given volume. Moreover, it is bounded and has finite perimeter.

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There exists a minimizer for $\lambda_{k,\Omega}$, $k \geq 3$, among all quasi-open sets Ω of given volume. Moreover, it is bounded and has finite perimeter.

However, it does not provide the shape of the minimizing domain!

Open problem

For $k \geq 3$, what is the bounded domain of volume 1 in \mathbb{R}^2 which minimizes $\lambda_{k,\Omega}$?

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~> **numerics !**

Numerical processing

Weak formulation of problem (\mathcal{P}) :

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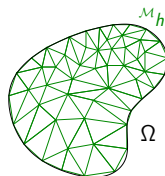
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\rightsquigarrow A discrete framework is required.

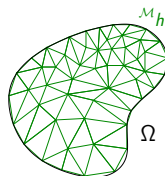
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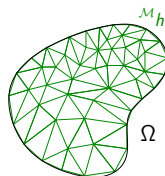


Instead of $H_0^1(\Omega)$ in (\mathcal{WP}) , consider the finite dimensional space

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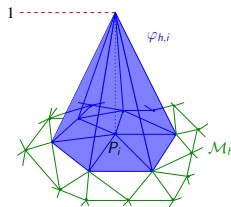


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Basis $\{ \varphi_{h,i} \}_{i=1}^N$ of V_h :

$$\varphi_{h,i}(P_j) = \delta_{ij},$$



$$(\mathcal{WP}_h) \left\{ \begin{array}{l} \text{find } u_h \in V_h, u_h \neq 0, \text{ and } \lambda > 0 \text{ such that} \\ \int_{\Omega} (\nabla u_h | \nabla \varphi_{h,i}) = \lambda \int_{\Omega} u_h \varphi_{h,i}, \quad \forall i = 1, \dots, N. \end{array} \right.$$

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Plugging $\mathbf{u}_h = \sum_{j=1}^N u_j \varphi_{h,j} \in V_h$ into (\mathcal{WP}_h) :

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\rightsquigarrow Lanczos algorithm to solve (\mathcal{WP}_h) .

Shape optimization

The idea is to use a descent algorithm to minimize the *cost functional* $J(\Omega) = \lambda_k(\Omega) \text{vol}(\Omega)$.

The first problem is to determine the domain of the functional J , that is the admissible shapes Ω .

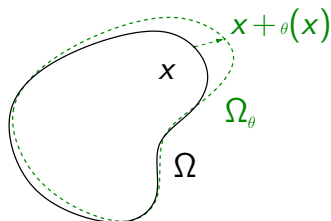
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Given an initial domain Ω , we allow deformations of the form

$$\Omega_\theta = (\text{id} + \theta)(\Omega), \quad \theta \in W^{1,\infty}(\Omega).$$



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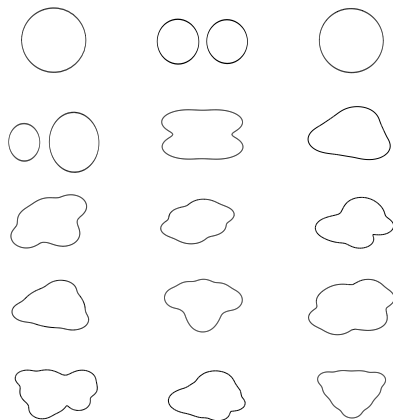
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Then, we obtain a new domain, we can mesh it, compute the associated eigenvalues and eigenfunctions, move the new boundary, and so on. . .

15 first candidates to be minimizing domains of volume 1 in \mathbb{R}^2 .

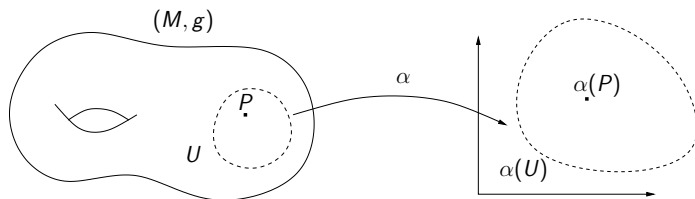


k	λ_k
1	18.17
2	36.39
3	46.30
4	64.78
5	78.53
6	89.05
7	106.51
8	120.01
9	134.06
10	144.82
11	160.55
12	174.37
13	188.84
14	202.22
15	211.16

Previously found by Oudet ('04, partly) and Antunes-Freitas ('12)

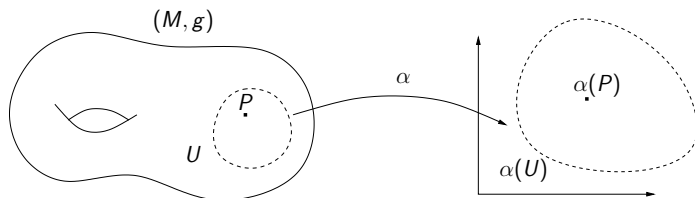
Generalization to surfaces

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Mesh $\alpha(U)$ in order to consider manifold non embeddable in \mathbb{R}^3 .

↪ use the expression of the Laplacian in local coordinates:

$$\Delta f = \frac{1}{\sqrt{\det(G)}} \sum_{j,k=1}^2 \partial_{x_j} \left(G^{jk} \sqrt{\det(G)} \partial_{x_k} f \right).$$

Generalization to surfaces

It implies several **modifications**. For instance,

- ▶ for the computation:

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- ▶ for the optimization:

There is no homothety any more! The volume constraint has to be taken into consideration. \rightsquigarrow **Lagrange multiplier**.

We look for a saddle point of the functional

$$J(\mu, \Omega) = \lambda_k(\Omega) + \mu(\text{vol}(\Omega) - V_0),$$

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↪ We get a similar formula for the shape optimization.

The algorithm gives the same results in \mathbb{R}^2 . ✓

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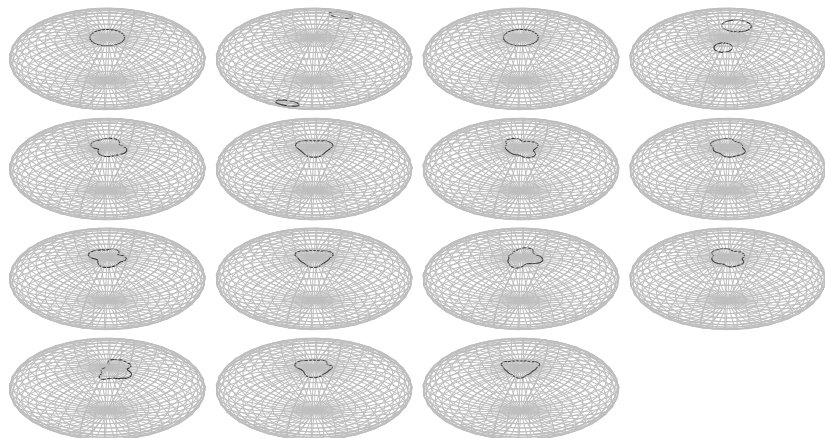
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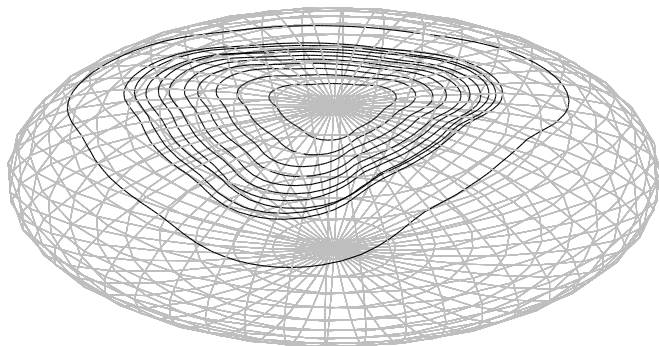
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- ▶ in the sphere \mathbb{S}^2 (curvature = + 1);
- ▶ in the Poincaré disc \mathbb{D}^2 (curvature = -1);
- ▶ in a hyperboloid H (curvature between 0 and 1)

$$H = \{(x, y, z) \in \mathbb{R}^3 \mid z > 0, x^2 + y^2 - z^2 = -1\}.$$



Optimal domains $\Omega_k^* \subset \mathbb{S}^2$ (volume 0.1) minimizing each of the first k eigenvalues.



Plot of the optimizers for $\lambda_{10}(\Omega_{10, \mathbb{S}^2}^*)$ and $\text{vol}(\Omega_{10, \mathbb{S}^2}^*) = 0.1, 0.2, \dots, 0.9, 1$ and 2 .

Comparison between manifolds

Comparison of the first eigenvalues for optimal domains of volume 0.01 in \mathbb{R}^2 , \mathbb{S}^2 , \mathbb{D}^2 and the hyperboloid H .

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$$\lambda_1(B_{\mathbb{S}^2,0.01}) < \lambda_1(B_{\mathbb{R}^2,0.01}) < \lambda_1(B_{\mathbb{D}^2,0.01}) < \lambda_1(B_{H,0.01})$$

\mathbb{R}^2	\mathbb{R}^2	\mathbb{R}^2	\mathbb{R}^2
1816.57	1816.80	1817.67	1819.10

Thank you for your attention !